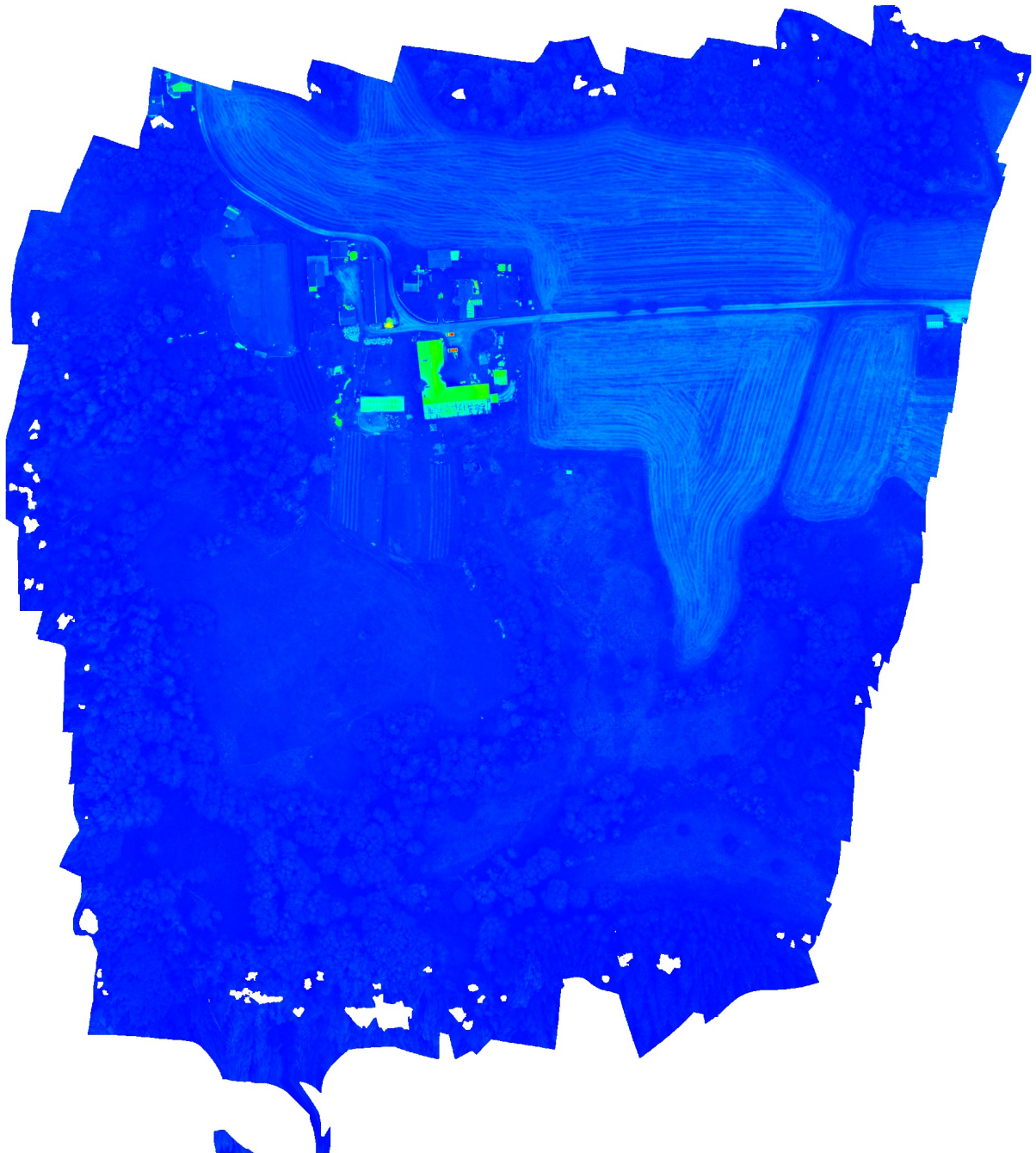


# Sander\_2022-09-29\_1\_AltumPT

Processing Report  
02 July 2024



# Survey Data

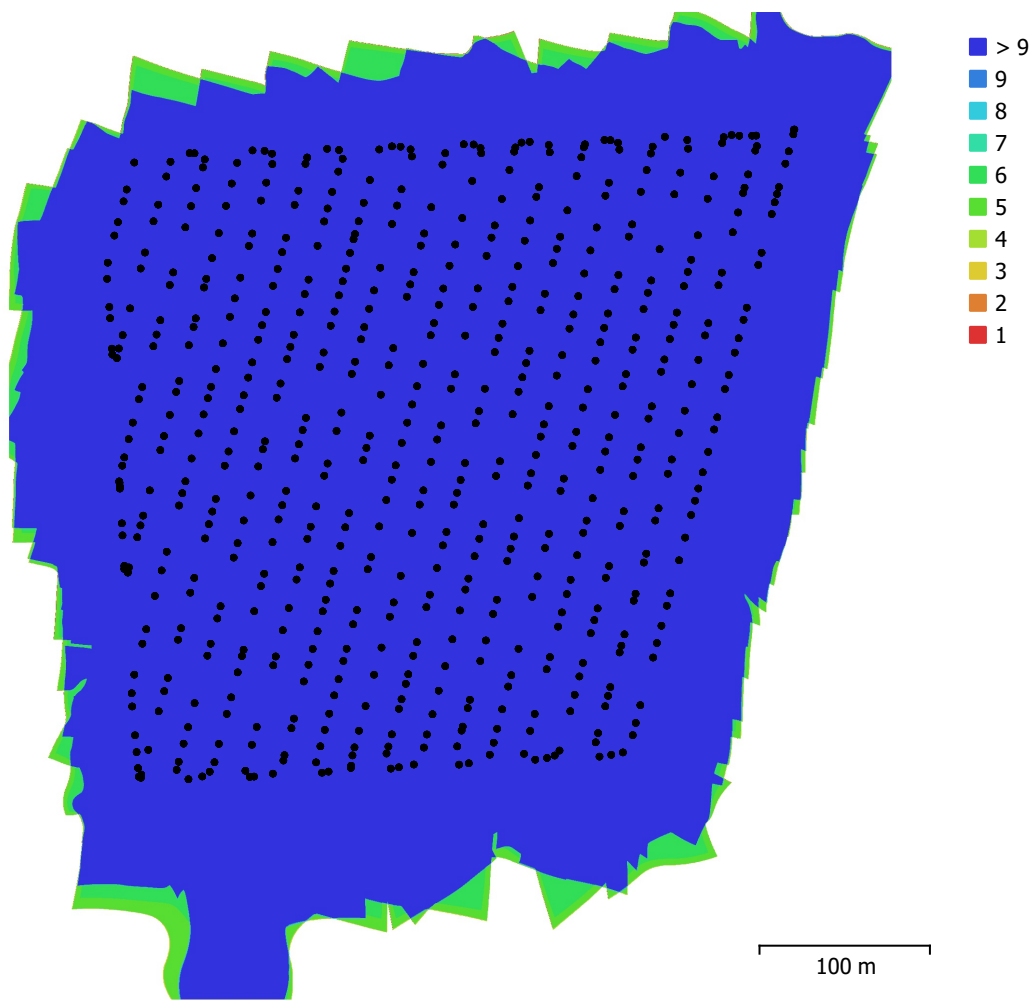


Fig. 1. Camera locations and image overlap.

Number of images:	4,151	Camera stations:	3,552
Flying altitude:	88.5 m	Tie points:	1,893,734
Ground resolution:	3.88 cm/pix	Projections:	11,972,540
Coverage area:	0.225 km <sup>2</sup>	Reprojection error:	0.525 pix

Camera Model	Resolution	Focal Length	Pixel Size	Precalibrated
Altum-PT, Blue (8mm)	2064 x 1544	8 mm	3.45 x 3.45 $\mu$ m	Yes
Altum-PT, Green (8mm)	2064 x 1544	8 mm	3.45 x 3.45 $\mu$ m	Yes
Altum-PT, Panchro (16.6...	4112 x 3008	16.6 mm	3.45 x 3.45 $\mu$ m	Yes
Altum-PT, Red (8mm)	2064 x 1544	8 mm	3.45 x 3.45 $\mu$ m	Yes
Altum-PT, Red edge (8m...	2064 x 1544	8 mm	3.45 x 3.45 $\mu$ m	Yes

<b>Camera Model</b>	<b>Resolution</b>	<b>Focal Length</b>	<b>Pixel Size</b>	<b>Precalibrated</b>
Altum-PT, NIR (8mm)	2064 x 1544	8 mm	3.45 x 3.45 $\mu\text{m}$	Yes

Table 1. Cameras.

# Camera Calibration

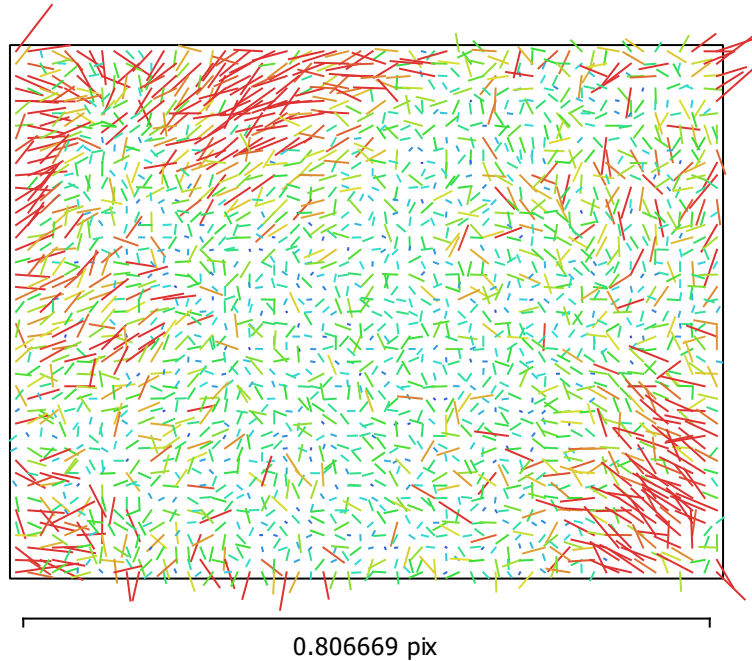


Fig. 2. Image residuals for Altum-PT, Blue (8mm).

## Altum-PT, Blue (8mm)

593 images, precalibrated

Type	Resolution	Focal Length	Pixel Size
<b>Frame</b>	<b>2064 x 1544</b>	<b>8 mm</b>	<b>3.45 x 3.45 <math>\mu</math>m</b>

	Value	Error	F	Cx	Cy	B1	B2	K1	K2	K3	P1	P2
<b>F</b>	<b>2277.92</b>	0.022	1.00	0.02	0.22	-0.13	0.04	-0.21	0.20	-0.17	-0.01	0.02
<b>Cx</b>	<b>4.90264</b>	0.014		1.00	0.03	-0.00	0.01	-0.00	0.00	-0.00	0.89	0.03
<b>Cy</b>	<b>-9.27201</b>	0.011			1.00	-0.05	0.01	0.01	-0.00	0.01	0.03	0.75
<b>B1</b>	<b>-0.182806</b>	0.0029				1.00	0.00	0.02	-0.04	0.05	-0.00	0.02
<b>B2</b>	<b>0.194983</b>	0.0028					1.00	-0.00	0.00	0.00	-0.04	-0.01
<b>K1</b>	<b>-0.125258</b>	5.3e-05						1.00	-0.97	0.92	0.00	0.01
<b>K2</b>	<b>0.149788</b>	0.00037							1.00	-0.98	-0.00	-0.00
<b>K3</b>	<b>-0.0271904</b>	0.00079								1.00	0.00	0.00
<b>P1</b>	<b>0.000334515</b>	1.7e-06									1.00	0.03
<b>P2</b>	<b>-4.15325e-05</b>	1.4e-06										1.00

Table 2. Calibration coefficients and correlation matrix.

# Camera Calibration

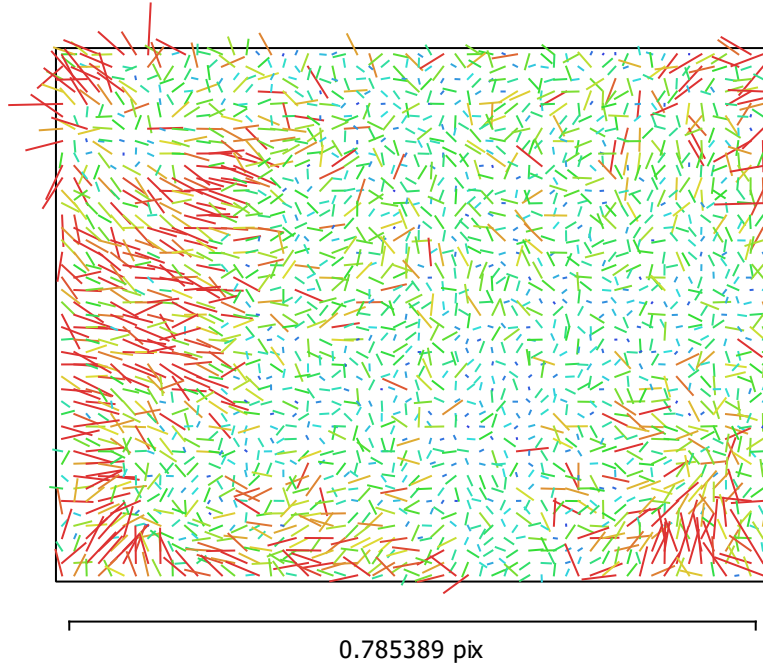


Fig. 3. Image residuals for Altum-PT, Green (8mm).

## Altum-PT, Green (8mm)

593 images, precalibrated

Type	Resolution	Focal Length	Pixel Size
<b>Frame</b>	<b>2064 x 1544</b>	<b>8 mm</b>	<b>3.45 x 3.45 <math>\mu</math>m</b>

	Value	Error	F	Cx	Cy	B1	B2	K1	K2	K3	P1	P2
<b>F</b>	<b>2278.33</b>	0.022	1.00	0.02	0.27	-0.12	0.04	-0.19	0.18	-0.15	-0.01	0.03
<b>Cx</b>	<b>0.0955909</b>	0.012		1.00	-0.01	-0.02	0.03	-0.01	0.01	-0.00	0.88	-0.01
<b>Cy</b>	<b>5.0611</b>	0.0096			1.00	-0.06	0.01	-0.00	0.01	-0.01	-0.01	0.71
<b>B1</b>	<b>-0.1541</b>	0.0027				1.00	-0.00	0.02	-0.04	0.04	-0.02	0.01
<b>B2</b>	<b>0.198118</b>	0.0027					1.00	-0.00	0.00	0.00	-0.03	-0.02
<b>K1</b>	<b>-0.130926</b>	4.7e-05						1.00	-0.97	0.92	-0.00	0.02
<b>K2</b>	<b>0.169967</b>	0.00033							1.00	-0.98	0.00	-0.00
<b>K3</b>	<b>-0.0678529</b>	0.0007								1.00	0.00	0.00
<b>P1</b>	<b>-0.000153702</b>	1.5e-06									1.00	-0.01
<b>P2</b>	<b>9.46286e-06</b>	1.2e-06										1.00

Table 3. Calibration coefficients and correlation matrix.

# Camera Calibration

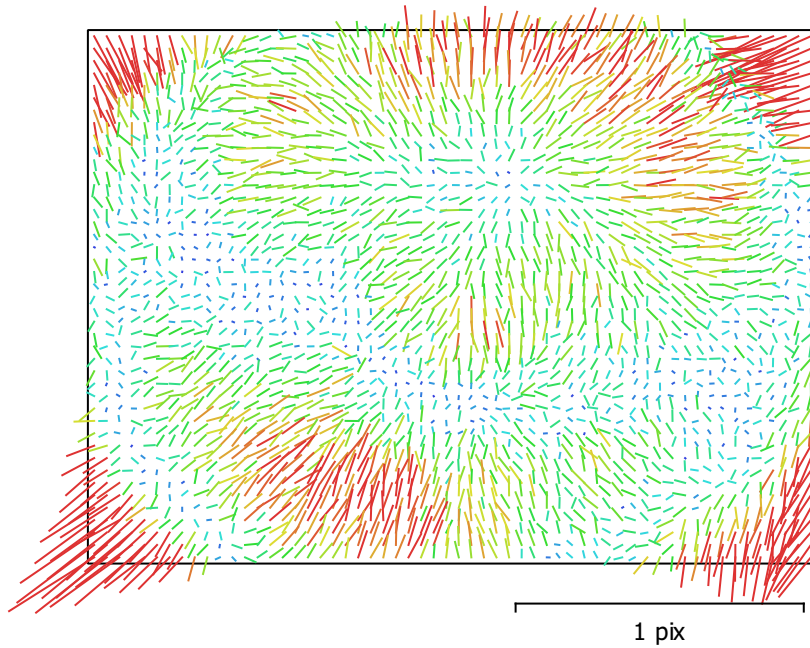


Fig. 4. Image residuals for Altum-PT, Panchro (16.6mm).

## Altum-PT, Panchro (16.6mm)

593 images, precalibrated

Type	Resolution	Focal Length	Pixel Size
<b>Frame</b>	<b>4112 x 3008</b>	<b>16.6 mm</b>	<b>3.45 x 3.45 <math>\mu</math>m</b>

	Value	Error	F	Cx	Cy	B1	B2	K1	K2	K3	K4	P1	P2
<b>F</b>	<b>4807.37</b>	0.047	1.00	0.01	0.31	-0.13	0.04	-0.24	0.22	-0.20	0.19	-0.00	0.06
<b>Cx</b>	<b>-17.6896</b>	0.02		1.00	-0.00	-0.01	0.03	-0.01	0.02	-0.02	0.02	0.87	-0.01
<b>Cy</b>	<b>-30.6302</b>	0.017			1.00	-0.06	0.02	-0.02	0.02	-0.03	0.03	0.00	0.72
<b>B1</b>	<b>-0.195968</b>	0.0056				1.00	0.00	0.03	-0.03	0.03	-0.02	-0.02	0.03
<b>B2</b>	<b>-0.077662</b>	0.0055					1.00	-0.00	-0.00	0.00	-0.00	-0.04	-0.02
<b>K1</b>	<b>-0.15122</b>	9.8e-05						1.00	-0.98	0.93	-0.89	-0.01	-0.00
<b>K2</b>	<b>0.297334</b>	0.0013							1.00	-0.99	0.96	0.01	0.01
<b>K3</b>	<b>0.0585981</b>	0.0069								1.00	-0.99	-0.01	-0.01
<b>K4</b>	<b>0.923679</b>	0.012									1.00	0.02	0.01
<b>P1</b>	<b>0.00062547</b>	1.4e-06										1.00	-0.00
<b>P2</b>	<b>0.000211669</b>	1.2e-06											1.00

Table 4. Calibration coefficients and correlation matrix.

# Camera Calibration

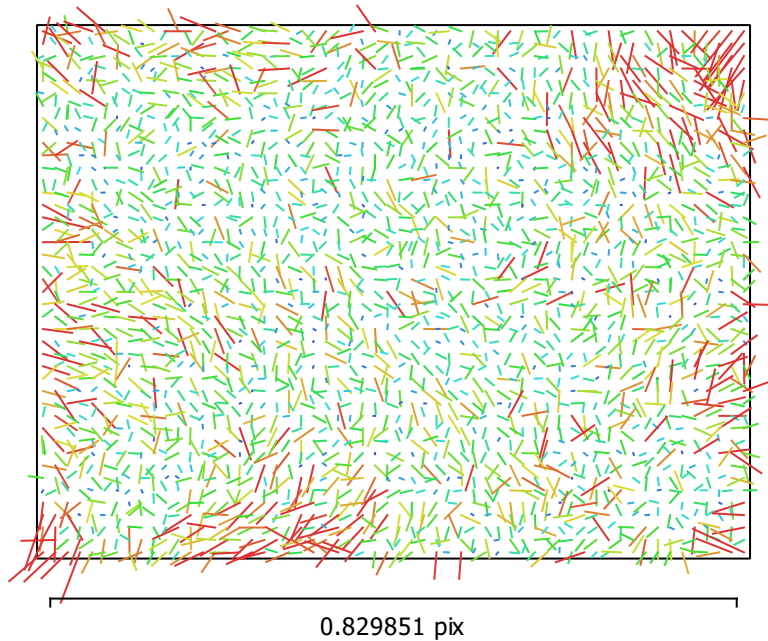


Fig. 5. Image residuals for Altum-PT, Red (8mm).

## Altum-PT, Red (8mm)

593 images, precalibrated

Type	Resolution	Focal Length	Pixel Size
<b>Frame</b>	<b>2064 x 1544</b>	<b>8 mm</b>	<b>3.45 x 3.45 <math>\mu\text{m}</math></b>

	Value	Error	F	Cx	Cy	B1	B2	K1	K2	P1	P2
<b>K3</b>	<b>-0.0775957</b>										
<b>F</b>	<b>2283.32</b>	0.022	1.00	0.02	0.24	-0.12	0.04	-0.16	0.20	-0.01	0.02
<b>Cx</b>	<b>-3.84584</b>	0.014		1.00	0.01	-0.01	0.01	-0.01	0.01	0.89	0.01
<b>Cy</b>	<b>0.285516</b>	0.011			1.00	-0.05	0.00	0.01	0.01	0.01	0.74
<b>B1</b>	<b>-0.182897</b>	0.003				1.00	0.00	-0.06	0.03	-0.01	0.01
<b>B2</b>	<b>-0.014836</b>	0.0029					1.00	-0.01	0.00	-0.03	-0.01
<b>K1</b>	<b>-0.136864</b>	2.2e-05						1.00	-0.96	0.01	0.03
<b>K2</b>	<b>0.178345</b>	6.9e-05							1.00	-0.01	-0.00
<b>P1</b>	<b>-1.27841e-05</b>	1.7e-06								1.00	0.01
<b>P2</b>	<b>-0.000245126</b>	1.4e-06									1.00

Table 5. Calibration coefficients and correlation matrix.

# Camera Calibration

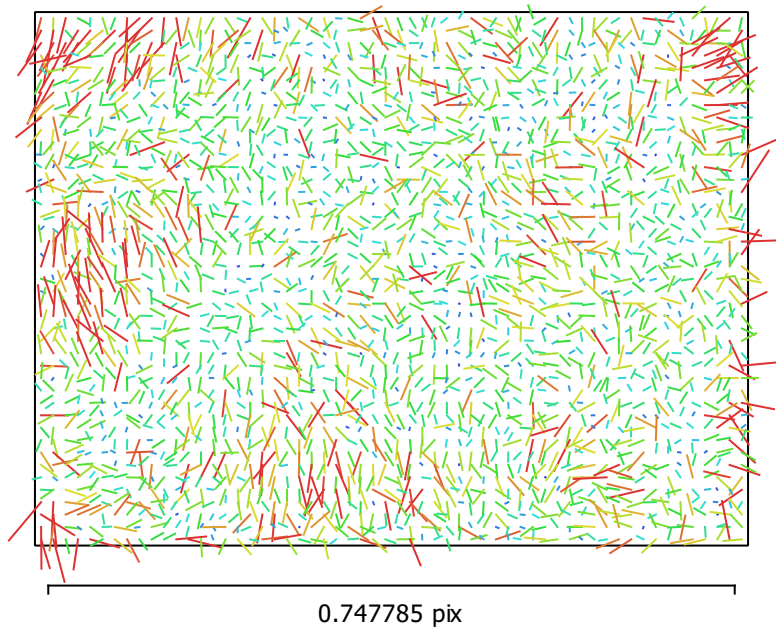


Fig. 6. Image residuals for Altum-PT, Red edge (8mm).

## Altum-PT, Red edge (8mm)

593 images, precalibrated

Type	Resolution	Focal Length	Pixel Size
<b>Frame</b>	<b>2064 x 1544</b>	<b>8 mm</b>	<b>3.45 x 3.45 <math>\mu</math>m</b>

	Value	Error	F	Cx	Cy	B1	B2	K1	K2	K3	P1	P2
<b>F</b>	<b>2282.63</b>	0.022	1.00	0.01	0.27	-0.12	0.04	-0.20	0.19	-0.15	-0.01	0.02
<b>Cx</b>	<b>-7.15688</b>	0.012		1.00	0.00	-0.00	0.02	-0.00	0.00	0.00	0.87	-0.00
<b>Cy</b>	<b>2.72055</b>	0.0098			1.00	-0.06	0.01	-0.00	0.01	-0.00	-0.00	0.70
<b>B1</b>	<b>-0.185929</b>	0.0028				1.00	0.00	0.02	-0.04	0.04	-0.00	0.02
<b>B2</b>	<b>0.0324608</b>	0.0027					1.00	-0.00	-0.00	0.00	-0.03	-0.01
<b>K1</b>	<b>-0.138167</b>	4.7e-05						1.00	-0.97	0.92	0.00	0.02
<b>K2</b>	<b>0.174147</b>	0.00034							1.00	-0.98	-0.00	-0.01
<b>K3</b>	<b>-0.0607904</b>	0.00071								1.00	-0.00	0.01
<b>P1</b>	<b>0.000119909</b>	1.5e-06									1.00	0.00
<b>P2</b>	<b>-1.35147e-05</b>	1.2e-06										1.00

Table 6. Calibration coefficients and correlation matrix.

# Camera Calibration

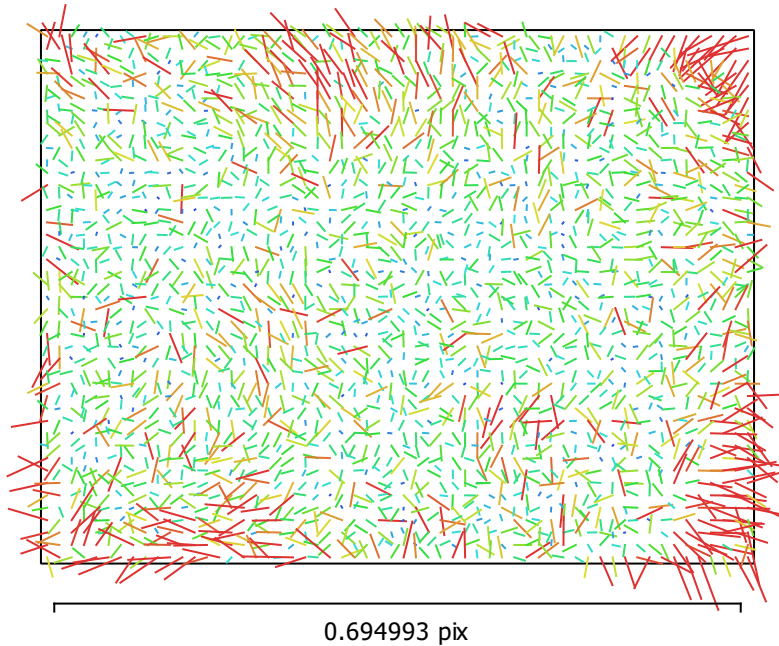


Fig. 7. Image residuals for Altum-PT, NIR (8mm).

## Altum-PT, NIR (8mm)

593 images, precalibrated

Type	Resolution	Focal Length	Pixel Size
<b>Frame</b>	<b>2064 x 1544</b>	<b>8 mm</b>	<b>3.45 x 3.45 μm</b>

	Value	Error	F	Cx	Cy	B1	B2	K1	K2	K3	P1	P2
<b>F</b>	<b>2285.46</b>	0.022	1.00	0.02	0.27	-0.12	0.04	-0.20	0.18	-0.15	-0.01	0.02
<b>Cx</b>	<b>2.58932</b>	0.012		1.00	-0.02	0.00	0.02	-0.00	0.00	0.00	0.87	-0.02
<b>Cy</b>	<b>1.64908</b>	0.0098			1.00	-0.07	0.01	-0.00	0.01	-0.01	-0.02	0.70
<b>B1</b>	<b>-0.218248</b>	0.0028				1.00	-0.00	0.02	-0.04	0.04	0.00	0.01
<b>B2</b>	<b>-0.108717</b>	0.0027					1.00	-0.00	0.00	0.00	-0.03	-0.00
<b>K1</b>	<b>-0.13827</b>	4.7e-05						1.00	-0.97	0.92	0.00	0.02
<b>K2</b>	<b>0.161557</b>	0.00033							1.00	-0.98	-0.00	-0.00
<b>K3</b>	<b>-0.0410563</b>	0.0007								1.00	0.00	0.00
<b>P1</b>	<b>-6.85292e-05</b>	1.4e-06									1.00	-0.01
<b>P2</b>	<b>-0.000147251</b>	1.2e-06										1.00

Table 7. Calibration coefficients and correlation matrix.

# Camera Locations

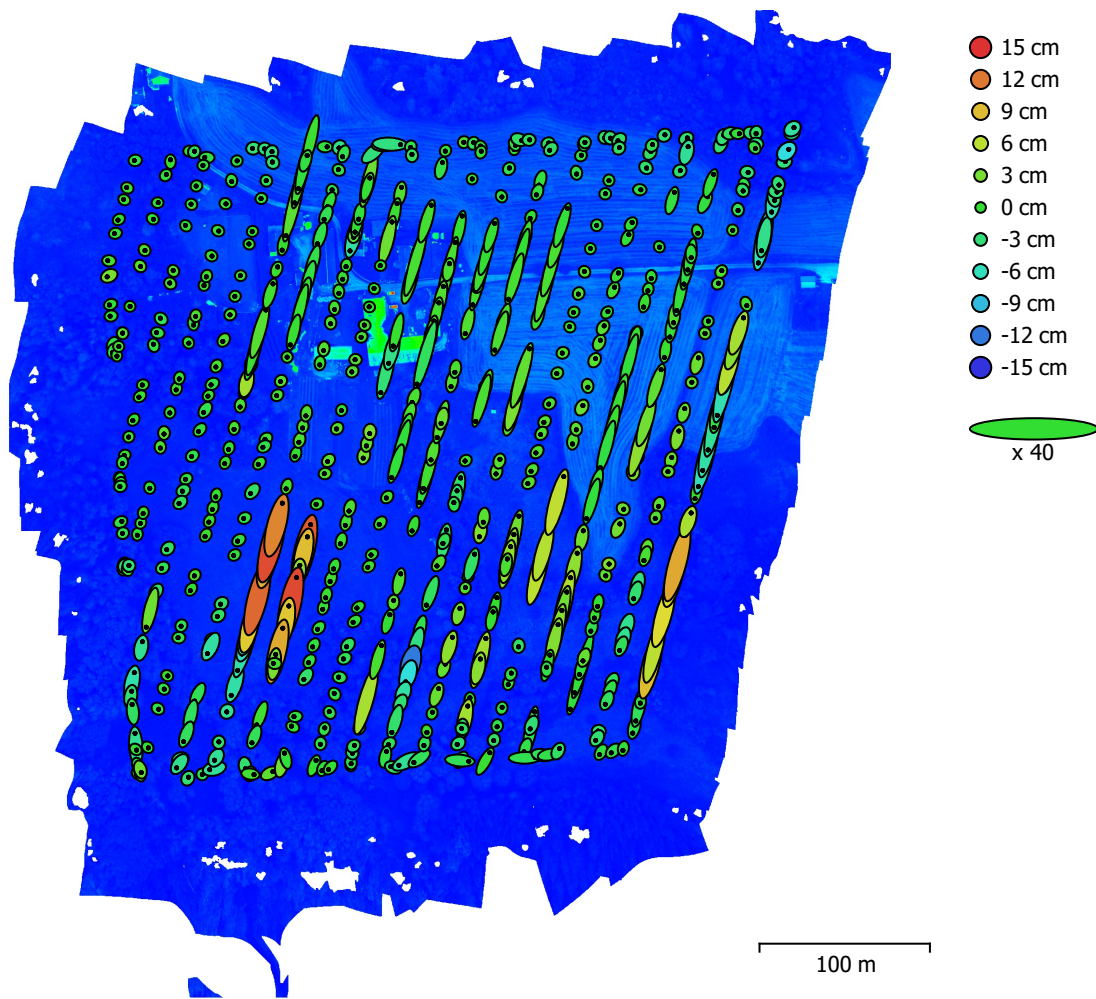


Fig. 8. Camera locations and error estimates.

Z error is represented by ellipse color. X,Y errors are represented by ellipse shape.

Estimated camera locations are marked with a black dot.

<b>X error (cm)</b>	<b>Y error (cm)</b>	<b>Z error (cm)</b>	<b>XY error (cm)</b>	<b>Total error (cm)</b>
8.23056	27.9741	2.66514	29.1597	29.2813

Table 8. Average camera location error.

X - Easting, Y - Northing, Z - Altitude.

# Ground Control Points

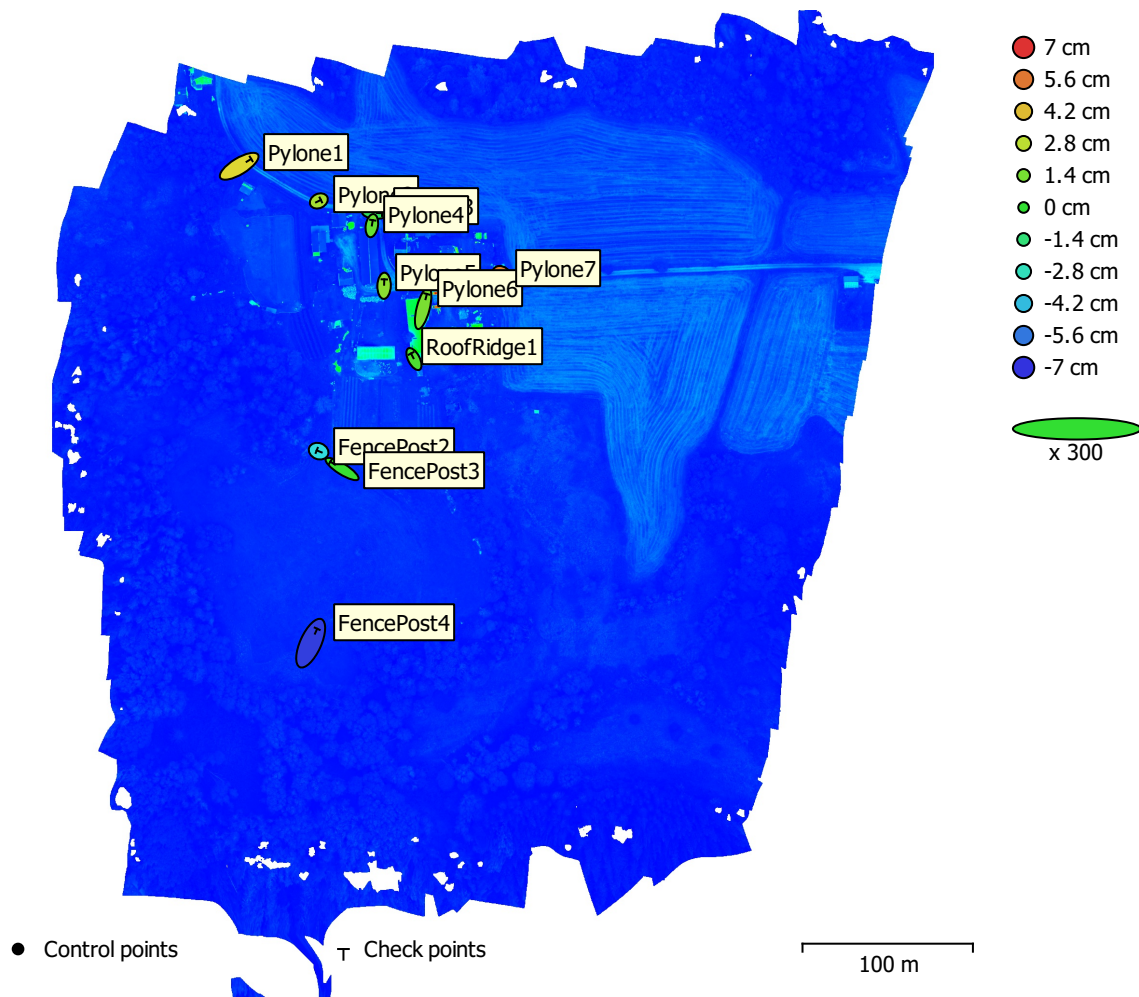


Fig. 9. GCP locations and error estimates.

Z error is represented by ellipse color. X,Y errors are represented by ellipse shape.

Estimated GCP locations are marked with a dot or crossing.

Count	X error (cm)	Y error (cm)	Z error (cm)	XY error (cm)	Total (cm)
11	2.37928	2.9661	3.20687	3.80246	4.97421

Table 9. Check points RMSE.

X - Easting, Y - Northing, Z - Altitude.

<b>Label</b>	<b>X error (cm)</b>	<b>Y error (cm)</b>	<b>Z error (cm)</b>	<b>Total (cm)</b>	<b>Image (pix)</b>
Pylone1	4.68985	2.85862	3.63326	6.58536	0.421 (6)
Pylone2	0.784733	0.387184	2.36044	2.51742	0.367 (6)
Pylone3	2.75904	-0.171699	-0.898501	2.90673	0.378 (6)
Pylone4	0.349897	2.14627	1.02453	2.40387	0.778 (6)
Pylone5	0.0760208	2.50216	1.8085	3.08825	0.326 (7)
Pylone6	1.46067	5.63119	1.47135	6.00072	0.350 (7)
Pylone7	-0.708347	1.0014	5.33032	5.46963	0.629 (6)
FencePost2	-0.749894	0.300865	-3.53559	3.62674	0.722 (5)
FencePost3	-4.57123	2.85835	0.131222	5.39291	0.410 (7)
FencePost4	2.55233	5.6388	-6.77029	9.17318	2.146 (5)
RoofRidge1	-1.14522	2.18796	0.540982	2.52811	0.717 (6)
<b>Total</b>	<b>2.37928</b>	<b>2.9661</b>	<b>3.20687</b>	<b>4.97421</b>	<b>0.775</b>

Table 10. Check points.  
X - Easting, Y - Northing, Z - Altitude.

# Digital Elevation Model

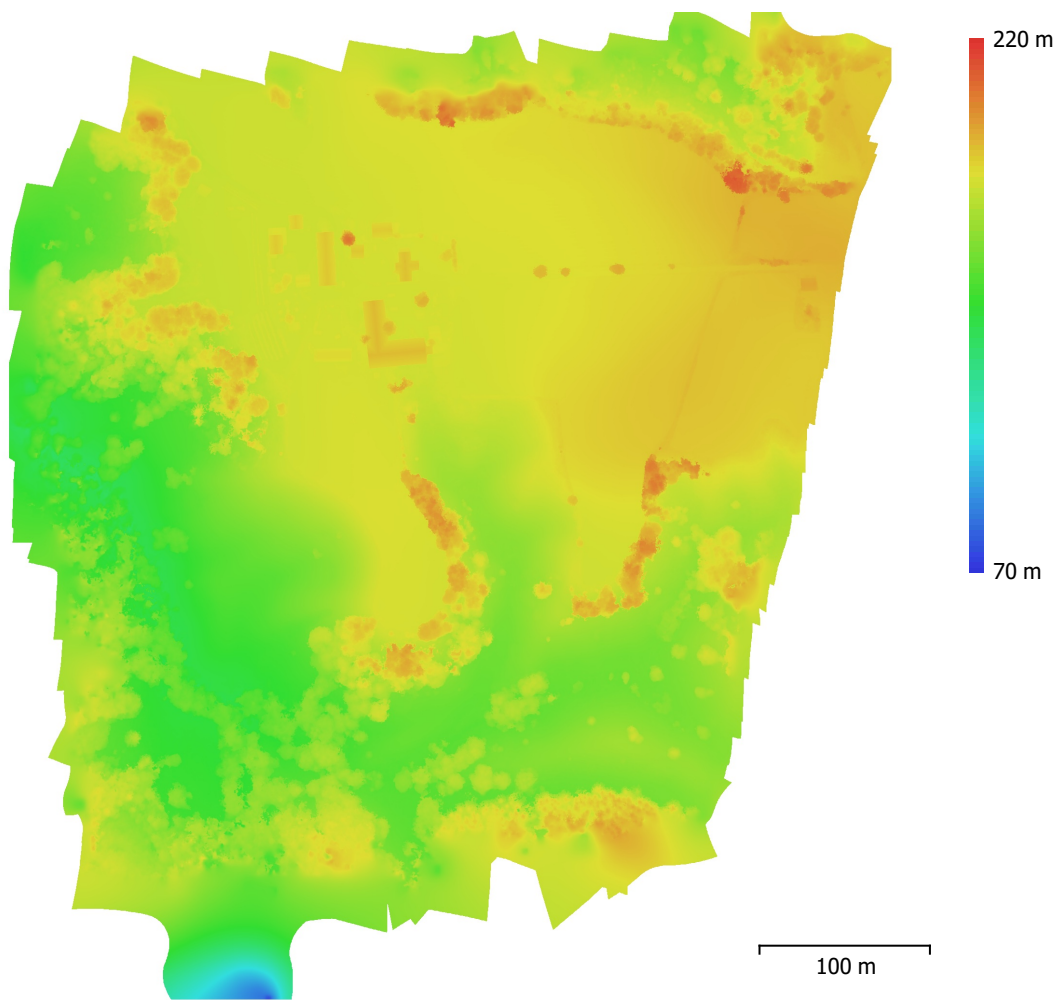


Fig. 10. Reconstructed digital elevation model.

Resolution: 5 cm/pix  
Point density: 400 points/m<sup>2</sup>

# Processing Parameters

<b>General</b>	
Cameras	4151
Aligned cameras	3552
Markers	11
Coordinate system	ETRS89 / UTM zone 32N + NN2000 height (EPSG::5972)
Rotation angles	Yaw, Pitch, Roll
<b>Tie Points</b>	
Points	1,893,734 of 2,208,948
RMS reprojection error	0.238612 (0.524622 pix)
Max reprojection error	0.940427 (50.7745 pix)
Mean key point size	2.05679 pix
Point colors	1 bands, uint16
Key points	No
Average tie point multiplicity	7.54879
<b>Alignment parameters</b>	
Accuracy	High
Generic preselection	Yes
Reference preselection	Source
Key point limit	40,000
Key point limit per Mpx	1,000
Tie point limit	4,000
Filter points by mask	No
Mask tie points	No
Exclude stationary tie points	Yes
Guided image matching	No
Adaptive camera model fitting	Yes
Matching time	17 minutes 7 seconds
Matching memory usage	5.71 GB
Alignment time	8 minutes 37 seconds
Alignment memory usage	9.63 GB
<b>Optimization parameters</b>	
Parameters	f, cx, cy, k1-k3, p1, p2
Adaptive camera model fitting	Yes
Optimization time	27 seconds
Date created	2024:07:02 11:48:20
Software version	2.1.0.17532
File size	810.87 MB
<b>Depth Maps</b>	
Count	592
<b>Depth maps generation parameters</b>	
Quality	High
Filtering mode	Mild
Max neighbors	16
Processing time	16 minutes 40 seconds
Memory usage	6.07 GB
Date created	2024:07:02 12:36:23
Software version	2.1.0.17532
File size	2.38 GB
<b>DEM</b>	
Size	10,346 x 11,587

Coordinate system ETRS89 / UTM zone 32N + NN2000 height (EPSG::5972)

**Depth maps generation parameters**

Quality High  
Filtering mode Mild  
Max neighbors 16  
Processing time 16 minutes 40 seconds  
Memory usage 6.07 GB

**Reconstruction parameters**

Source data Depth maps  
Interpolation Enabled  
Processing time 9 minutes 8 seconds  
Memory usage 11.72 GB  
Date created 2024:07:02 12:45:32  
Software version 2.1.0.17532  
File size 388.92 MB

**Orthomosaic**

Size 20,680 x 23,160  
Coordinate system ETRS89 / UTM zone 32N + NN2000 height (EPSG::5972)  
Colors 7 bands, uint16

**Reconstruction parameters**

Blending mode Mosaic  
Surface DEM  
Enable hole filling Yes  
Enable ghosting filter No  
Processing time 19 minutes 3 seconds  
Memory usage 3.48 GB  
Date created 2024:07:02 13:24:07  
Software version 2.1.0.17532  
File size 93.62 GB

**Raster Transform**

Expression B1/16384; B2/16384; B4/16384; B5/16384; B6/16384; B7/100-273.15; B3...

**System**

Software name Agisoft Metashape Professional  
Software version 2.1.0 build 17532  
OS Windows 64 bit  
RAM 127.15 GB  
CPU AMD Ryzen 9 7950X 16-Core Processor  
GPU(s) NVIDIA GeForce RTX 4080 SUPER