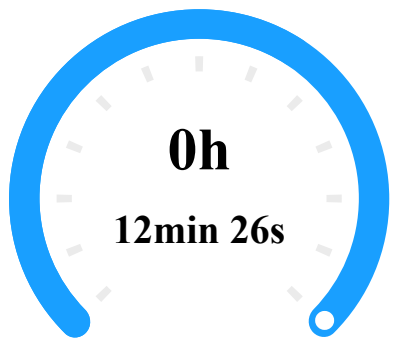


DJI Terra Quality Report

V4.1.0 | 2024-07-02 09:51 | Mission: Sander_2022-07-12_L1

Quality Report for LiDAR Point Cloud Processing

Aircraft Data Collection Time



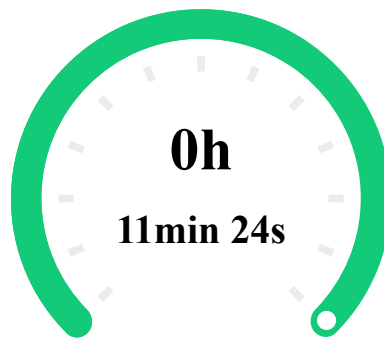
POS Data Collection Time

12min 26s

Point Cloud Data Collection Time

9min 53s

Software Processing Time



Point Cloud Optimization Time ^

- Point Cloud Accuracy Optimization Time
- Point Cloud Colorization Time
- Output Saving Time
- Others

7min 29s

2min 32s

24s

1min 6s

3min 26s

Ground Point Classification Time

1min 49s

DEM Generation Time

2min 4s

Reconstruction Parameters

Point Cloud Optimization Parameters

| | |
|--------------------------------------|------------------------|
| Use custom base station data | No |
| Scenario | Point Cloud Processing |
| Point Cloud Density (By Percentage) | High |
| Point Cloud Effective Distance Range | 3-300 m |
| Accuracy Control and Check | No |
| Optimize Point Cloud Accuracy | Yes |
| Smooth Point Cloud | No |

Point Cloud Output Parameters

| | |
|--|---------------------------------------|
| Ground Point Classification | Yes |
| Ground Point Classification Parameters | Gentle Slope 20 m 6° 0.5 m |
| DEM | Yes |
| DEM Parameters | By GSD 0.1 m |
| Contour | No |
| Point Cloud Format | PNTS LAS |
| Merged Output | No |
| LiDAR Point Cloud Block Count | 1 |
| Output Coordinate System | WGS 84 / UTM zone 32N NN2000 height |

Mission Parameters

Aircraft Parameters (Aircraft 1)

Hardware Parameters

| | |
|------------------|---|
| Payload | DJI Zenmuse L1 |
| Payload SN | 3FCDJ9N00455MK |
| LiDAR Parameters | https://enterprise.dji.com/zenmuse-l1/specs |

LiDAR and IMU Calibration Parameters

| Parameters | X (m) | Y (m) | Z (m) | roll (rad) | pitch (rad) | yaw (rad) |
|--------------------|---------|---------|----------|------------|-------------|-----------|
| Before Calibration | 0.03508 | 0.01694 | -0.04644 | 3.1261957 | -0.0003296 | 0.0035991 |

Flight Parameters (1 Flights)

| | |
|----------------------|------------|
| Average Flight Speed | 3.64m/s |
| Flight Height | 81.29m |
| Ground Beam Diameter | 406mm*40mm |
| Pulse Rate | 240kHz |
| Scan Rate | 720kHz |

System Parameters

| | |
|-----------|--|
| CPU | AMD Ryzen 9 7950X 16-Core Processor 32 cores |
| GPU Count | 1 |
| GPU 0 | NVIDIA GeForce RTX 4090 |
| RAM | 130805 M |

Accuracy Parameters

POS Status

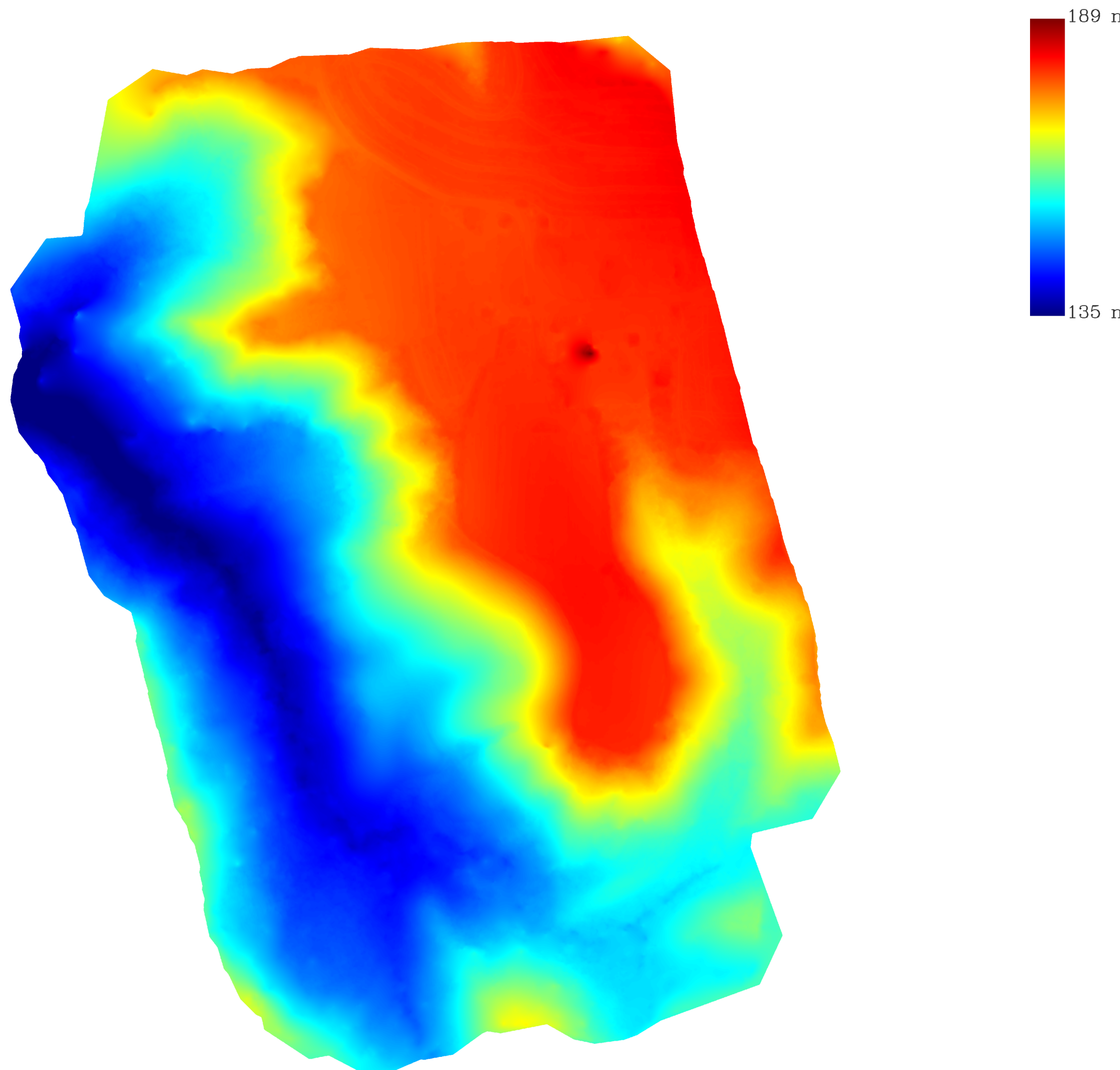
| | |
|-------|---------|
| Fix | 100.00% |
| Other | 0.00% |

IMU Trajectory Error

| Parameters | X(E) RMSE | Average X(E) | Y(N) RMSE | Average Y(N) | Z(U) RMSE | Average Z(U) |
|------------|---------------|---------------|---------------|---------------|---------------|---------------|
| Location | 0.00013 m | 0.00698 m | 0.00008 m | 0.00562 m | 0.00009 m | 0.00575 m |
| Attitude | 0.0000071 rad | 0.0001759 rad | 0.0000044 rad | 0.0001842 rad | 0.0000748 rad | 0.0005663 rad |

Output Preview

DEM



Output Parameters

Point Cloud Density

| Scale | Point Cloud Average Density | Point Cloud Standard Density | Grid Side Length | Total Grid Number | Non-conforming Grid Ratio |
|--------|-----------------------------|------------------------------|------------------|-------------------|---------------------------|
| 1:500 | 796points/m² | 16points/m² | 0.25 m | 1981944 | 2.52% |
| 1:1000 | 796points/m² | 4points/m² | 0.5 m | 503656 | 1.62% |
| 1:2000 | 796points/m² | 1points/m² | 1 m | 128084 | 1.69% |

Output List

PNTS | LAS | DEM TIF | DEM Tile